

Applications of Malliavin Calculus in Statistical Inference

José M. Corcuera

Faculty of Mathematics
University of Barcelona

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Consider a probability space (Ω, \mathcal{F}, P) and a Gaussian subspace \mathcal{H} of $L^2(\Omega, \mathcal{F}, P)$ whose elements are zero-mean Gaussian random variables. Let \mathfrak{H} be a separable Hilbert space with scalar product denoted by $\langle \cdot, \cdot \rangle_{\mathfrak{H}}$ and norm $\| \cdot \|_{\mathfrak{H}}$, we will assume there is an isometry

$$\begin{aligned} W : \mathfrak{H} &\rightarrow \mathcal{H} \\ h &\mapsto W(h) \end{aligned}$$

that is

$$E(W(h_1)W(h_2)) = \langle h_1, h_2 \rangle_{\mathfrak{H}},$$

Let \mathcal{S} be the class of smooth random variables $T(W(h_1), \dots, W(h_n))$ such that T and all its derivatives have polynomial growth. Given $T \in \mathcal{S}$ we can define its differential as

$$DT = \sum_{i=1}^n \partial_i T(W(h_1), W(h_2), \dots, W(h_n)) h_i.$$

DT can be seen as a random variable with values in \mathfrak{H} .

Then we can define the derivative operator as

$$D : \mathbb{D}^{1,2} \subseteq L^2(\Omega, \mathbb{R}) \longrightarrow L^2(\Omega, \mathfrak{H})$$

$$T \longmapsto DT.$$

where $\mathbb{D}^{1,2}$ is the closure of the class of smooth random variables with respect to the norm

$$\|T\|_{1,2} = \left(E(|T|^2) + E(\|DT\|_{\mathfrak{H}}^2) \right)^{1/2}$$

Let u be an element of $L^2(\Omega, \mathfrak{H})$ and assume there is an element $\delta(u)$ belonging to $L^2(\Omega)$ and such that

$$E(\langle DT, u \rangle_{\mathfrak{H}}) = E(T\delta(u))$$

for any $T \in \mathbb{D}^{1,2}$, then we say that u belongs to the domain of δ (denoted by $dom(\delta)$) and that δ is the adjoint operator of D .

In the following results we assume that our observations are expressed as the measurable map

$$\begin{aligned} X : \Omega \times \Theta &\rightarrow \mathbb{R}^n \\ (\omega, \theta) &\mapsto x = X(\omega, \theta), \end{aligned}$$

Θ an open subset of \mathbb{R} with the Borelian σ -field and the σ -field in Ω is the σ -field generated by \mathcal{H} .

Theorem

Let $X_j \in \mathbb{D}^{1,2}$, $j = 1, \dots, n$ and Z be a random variable with values in \mathfrak{H} , in the domain of δ , such that

$$\langle Z, DX_j \rangle_{\mathfrak{H}} = \partial_{\theta} X_j. \quad (1)$$

assume that

- i) X has density $p(x; \theta) \in C^1$ as function of θ with support, $\text{supp}(X)$, independent of θ ,
- ii) Any smooth statistic with compact support in the interior of $\text{supp}(X)$ is regular: $\partial_{\theta} \int_{\mathbb{R}^n} T(x) p(x; \theta) dx = \int_{\mathbb{R}^n} T(x) \partial_{\theta} p(x; \theta) dx$, for all $\theta \in \Theta$,

then

$$E(\delta(Z)|X) = \partial_{\theta} \log p(X; \theta), \text{ a.s. and for all } \theta \in \Theta.$$

Proof.

$$\partial_{\theta} E_{\theta}(T(X)) = \sum_{k=1}^n E(\partial_{x_k} T(X) \partial_{\theta} X_k).$$

If we have Z with

$$\langle Z, DX_j \rangle_{\mathfrak{H}} = \partial_{\theta} X_j$$

then

$$\partial_{\theta} E(T(X)) = E(\partial_{x_k} T(X) \langle Z, DX_k \rangle_{\mathfrak{H}}).$$

By the chain rule for the derivative operator D ,

$$DT(X) = \partial_{x_k} T(X) DX_k,$$

then

$$\begin{aligned} \partial_{\theta} E(T(X)) &= E(\langle Z, DT(X) \rangle_{\mathfrak{H}}) \\ &= E(T(X) \delta(Z)). \end{aligned}$$

Proof (Cont.) Next, we have

$$\begin{aligned}
 E(T(X)\delta(Z)) &= \partial_{\theta} E(T(X)) \\
 &= \partial_{\theta} \int_{\mathbb{R}^n} T(x)p(x; \theta) dx \\
 &= \int_{\mathbb{R}^n} T(x)\partial_{\theta} p(x; \theta) dx \\
 &= \int_{\mathbb{R}^n} T(x)\partial_{\theta} \log p(x; \theta)p(x; \theta) dx \\
 &= E(T(X)\partial_{\theta} \log p(X; \theta)).
 \end{aligned}$$

Therefore

$$E((\delta(Z) - \partial_{\theta} \log p(X; \theta))T(X)) = 0.$$

The next goal is to provide a somewhat standard way of finding Z . For example, if there exists U , an n -dimensional random vector with values on H such that

$$\langle U_k, DX_j \rangle_{\mathfrak{H}} = \delta_{kj}$$

where δ_{kj} is Kronecker's delta then

$$Z = \sum_{k=1}^n U_k \partial_{\theta} X_k$$

verifies condition (1) if $Z \in \text{dom}(\delta)$. In particular, if

$$(A_{kj}) = (\langle DX_k, DX_j \rangle_{\mathfrak{H}})^{-1}$$

is well defined then we can take

$$U_k = \sum_{j=1}^n A_{kj} DX_j.$$

Example. Let $X^{(n)} = (X_{t_1}, X_{t_2}, \dots, X_{t_n})$, $0 < t_1 < t_2 \dots < t_n$, be observations of the Ornstein-Uhlenbeck process

$$dX_t = -\theta X_t dt + dB_t, t \geq 0, \quad X_0 = 0.$$

Or, by integrating,

$$X_t = \int_0^t e^{-\theta(t-s)} dB_s.$$

Where B_t , $t \geq 0$ is a standard Brownian motion. Let \mathcal{H} be the closed linear space generated by the random variables $\{B_t, 0 \leq t \leq T\}$ and $\mathfrak{H} = L^2([0, T], dx)$. Then the map

$$\begin{aligned} W : \mathfrak{H} &\rightarrow \mathcal{H} \\ \mathbf{1}_{[0,t]}(\cdot) &\mapsto W(\mathbf{1}_{[0,t]}) \equiv \int_0^T \mathbf{1}_{[0,t]}(s) dB_s = B_t \end{aligned}$$

defines a linear isometry, and $W(h)$ is the stochastic integral of the function h . Consequently

$$DX_t = e^{-\theta(t-\cdot)} \mathbf{1}_{[0,t]}(\cdot).$$

We have

$$\begin{aligned}\partial_{\theta} X_t &= - \int_0^t e^{-\theta(t-s)} X_s ds \\ &= - \int_0^T X_s D_s X_t ds = - \langle X, DX_t \rangle_{\mathfrak{H}},\end{aligned}$$

where we write $DX_t(s) = D_s X_t$. Then

$$\begin{aligned}\partial_{\theta} \log p(X^{(n)}; \theta) &= -E(\delta(X)|X^{(n)}) = -E\left(\int_0^T X_s dB_s | X^{(n)}\right) \\ &= -E\left(\int_0^T X_s dX_s + \theta \int_0^T X_s^2 ds | X^{(n)}\right)\end{aligned}$$

In particular the maximum likelihood estimator of θ is given by

$$\hat{\theta} = - \frac{E\left(\int_0^T X_s dX_s | X^{(n)}\right)}{E\left(\int_0^T X_s^2 ds | X^{(n)}\right)}.$$

Let $X^{(n)} = (X_{t_1}, X_{t_2}, \dots, X_{t_n})$, $0 = t_0 < t_1 < t_2 \dots < t_n$, where

$$X_t = x + \int_0^t b_s(\theta, X_s) ds + \int_0^t \sigma_s(\theta, X_s) dB_s.$$

and B is a standard Brownian motion.

$$DX_t = \partial_x X_t (\partial_x X_t)^{-1} \sigma_s(\theta, X_s) \mathbf{1}_{[0,t]}(\cdot),$$

Define

$$\beta_t = (\partial_x X_t)^{-1} \partial_\theta X_t$$

and

$$\tilde{\beta}_t = \partial_x X_t (\sigma_t(\theta, X_t))^{-1} \sum_{i=1}^n a(t) (\beta_{t_i} - \beta_{t_{i-1}}) \mathbf{1}_{\{t_{i-1} \leq t < t_i\}},$$

where

$$a \in L^2[0, T], \int_{t_{i-1}}^{t_i} a(t) dt = 1, i = 1, \dots, n.$$

Then, it is easy to see that

$$\partial_{\theta} X_{t_i} = \langle \tilde{\beta}, DX_{t_i} \rangle_{\mathfrak{H}}.$$

Consequently the score function is given by

$$E(\delta(\tilde{\beta}) | X^{(n)}),$$

where

$$\begin{aligned} \delta(\tilde{\beta}) &= \sum_{i=1}^n (\beta_{t_i} - \beta_{t_{i-1}}) \int_{t_{i-1}}^{t_i} a(t) \partial_x X_t (\sigma_t(\theta, X_t))^{-1} dB_t \\ &\quad - \sum_{i=1}^n \int_{t_{i-1}}^{t_i} a(t) D_t \beta_{t_i} \partial_x X_t (\sigma_t(\theta, X_t))^{-1} dt \end{aligned}$$

Let $\Delta t_i := t_i - t_{i-1} = 1/n$, and consider n observations, we obtain

$$E(\delta(\tilde{\beta})|X^{(n)}) = n \sum_{i=1}^n \left\{ \frac{\partial_{\theta} \sigma_{t_{i-1}}}{\sigma_{t_{i-1}}^3} (\Delta X_{t_i})^2 - \frac{1}{n} \frac{\partial_{\theta} \sigma_{t_{i-1}}}{\sigma_{t_{i-1}}} \right\} + O(1). \quad (2)$$

If we define

$$Z_n(\theta, \theta + \frac{u}{\sqrt{n}}) = \log p(X^{(n)}; \theta + \frac{u}{\sqrt{n}}) - \log p(X^{(n)}; \theta)$$

$$Z_n(\theta, \theta + \frac{u}{\sqrt{n}}) = \int_{\theta}^{\theta + u/\sqrt{n}} E(\delta(\tilde{\beta})|X^{(n)}) d\theta$$

From (2) we can deduce that

$$Z_n(\theta, \theta + \frac{u}{\sqrt{n}}) \xrightarrow{\mathcal{L}} u \int_0^1 \sqrt{2} \frac{\partial_\theta \sigma_s}{\sigma_s} dW_s - \frac{u^2}{2} \int_0^1 2 \left(\frac{\partial_\theta \sigma_s}{\sigma_s} \right)^2 ds,$$

that is the model satisfies the LAMN property. In particular this implies that the asymptotic Fisher information for θ is given by

$$2 \int_0^1 \left(\frac{\partial_\theta \sigma_s}{\sigma_s} \right)^2 ds.$$

Assume that our vector of observations $Z^{(n)}$ has parts in a Gaussian space (\mathcal{G} -measurable random variables \mathcal{G} is the σ -field generated by \mathcal{H} , and parts "out" of a Gaussian space: independent of \mathcal{G}). For instance

$$Z_k = F(\theta, X_k, Y_k), k = 1, \dots, n$$

where $X^{(n)} = (X_1, \dots, X_n)$ is a \mathcal{G} -measurable random vector and $Y^{(n)} = (Y_1, \dots, Y_n)$ is independent of \mathcal{G} . Let T be a regular statistics $T = T(Z^{(n)})$. Then we have

$$\begin{aligned} \partial_\theta E_\theta(T) &= \partial_\theta E(T(Z^{(n)})) = E(\partial_\theta T(Z^{(n)})) \\ &= E(\partial_{Z_i} T(Z^{(n)}) \partial_\theta Z_i). \end{aligned}$$

Now we can *define*

$$DZ_k := \partial_{X_k} FDX_k$$

where DX_k is the derivative when we are in a Gaussian space.

Also we can define the adjoint operator in the same way and with similar properties, in particular we have that if u is an element of $L^2(\Omega, \mathfrak{H})$ then we can write

$$E(\langle DT, u \rangle_{\mathfrak{H}}) = E(T\delta(u))$$

where δ is the adjoint operator of D and whenever u is in the domain of δ .

We have

$$DT = \partial_{Z_i} T(Z^{(n)}) DZ_i = \partial_{Z_i} T(Z^{(n)}) \partial_{X_i} FDX_i,$$

and by using the duality property, if we have a random variable V with values in \mathfrak{H} (and in the domain of δ) such that

$$\langle DZ_i, V \rangle_{\mathfrak{H}} = \partial_{\theta} Z_i$$

then

$$\partial_{\theta} \log p(Z^{(n)}; \theta) = E(\delta(V) | Z^{(n)}).$$

Let $X^{(n)} = (X_{t_1}, X_{t_2}, \dots, X_{t_n})$, $0 = t_0 < t_1 < t_2 \dots < t_n$, where

$$X_t = x + \int_0^t b_s(\theta, X_s) ds + \int_0^t \sigma_s(\theta, X_s) dB_s + \int_0^t c_{s,z}(\theta, X_{s-}) M(dz, ds).$$

Where $M(dx, ds)$ is a Poisson random measure with intensity $\nu(dz, ds) = \nu_s(dz) ds$ and B is an independent standard Brownian motion.

We again have

$$dX_t = \partial_x X_t (\partial_x X_t)^{-1} \sigma(\theta, X_t) \mathbf{1}_{[0, t]}(\cdot).$$

Then ,

$$\partial_\theta \log p(x; \theta) = E(\delta(\tilde{\beta}) | X^{(n)} = x),$$

where

$$\begin{aligned} \delta(\tilde{\beta}) &= \sum_{i=1}^n (\beta_{t_i} - \beta_{t_{i-1}}) \int_{t_{i-1}}^{t_i} a(t) \partial_x X_t (\sigma_t(\theta, X_t))^{-1} dB_t \\ &\quad - \sum_{i=1}^n \int_{t_{i-1}}^{t_i} a(t) D_t \beta_{t_i} \partial_x X_t (\sigma_t(\theta, X_t))^{-1} dt. \end{aligned}$$

If we take $\Delta t_i := t_i - t_{i-1} = 1/n$, and n observations, we have that

$$Z_n(\theta, \theta + \frac{u}{\sqrt{n}}) \xrightarrow{\mathcal{L}} u \int_0^1 \sqrt{2} \frac{\partial_\theta \sigma_s}{\sigma_s} dW_s - \frac{u^2}{2} \int_0^1 2 \left(\frac{\partial_\theta \sigma_s}{\sigma_s} \right)^2 ds,$$

that is, the model satisfies the LAMN property too.

Let Y_t be an observation of a compound Poisson process of parameter λ and with jumps given by a random variable X . Then

$$\begin{aligned}
 \partial_\lambda E(\mathbf{1}_{\{Y_t \in A\}}) &= \partial_\lambda \sum_{n=0}^{\infty} \frac{e^{-\lambda t} (\lambda t)^n}{n!} P(X_1 + \dots + X_n \in A) \\
 &= -t \sum_{n=0}^{\infty} \left(\frac{e^{-\lambda t} (\lambda t)^n}{n!} - \frac{ne^{-\lambda t} (\lambda t)^{n-1}}{n!} \right) P(X_1 + \dots + X_n \in A) \\
 &= -tP(Y_t \in A) + \frac{1}{\lambda} \sum_{n=0}^{\infty} \frac{e^{-\lambda t} (\lambda t)^n}{n!} nP(X_1 + \dots + X_n \in A) \\
 &= -tE(\mathbf{1}_{\{Y_t \in A\}}) + \frac{1}{\lambda} E(\mathbf{1}_{\{Y_t \in A\}} N_t) = E(\mathbf{1}_{\{Y_t \in A\}} (\frac{N_t}{\lambda} - t)) \\
 &= E(\mathbf{1}_{\{Y_t \in A\}} (\frac{N_T}{\lambda} - T)).
 \end{aligned}$$

So the score function is given by

$$E\left(\frac{N_T}{\lambda} - T \mid Y_t\right)$$

Suppose now that our observations are Y_{t_1}, \dots, Y_{t_n} , $0 < t_1 < \dots < t_n \leq T$. Then, since the increments are independent, the score function is given by

$$E\left(\frac{N_T}{\lambda} - T \mid Y_{t_1}, Y_{t_2}, \dots, Y_{t_n}\right)$$

The trajectories of a compound process can be described by indicating the time and amplitude of the jumps. So $\Omega = \bigcup_{n=0}^{\infty} (\mathbb{R}_+ \times \mathbb{R})^n$ could serve for this purpose and if $\omega \in \bigcup_{n=0}^{\infty} (\mathbb{R}_+ \times \mathbb{R})^n$, $\omega = ((s_1, x_1), \dots, (s_k, x_k))$ for certain natural k . In this space we assume that $s_j - s_{j-1} \sim \exp(\lambda)$ $x_j \sim f(x)$ and all are independent. Then if we consider the random variables

$$Y_t : \Omega \rightarrow \mathbb{R}$$

$$((s_1, x_1), \dots, (s_k, x_k)) \rightarrow Y_t(\omega) = \sum_{i=1}^k x_i \mathbf{1}_{[s_i, \infty]}(t),$$

$(Y_t)_{t \geq 0}$ is a compound Poisson process.

We have that

$$\begin{aligned}
 & \partial_\lambda E(\mathbf{1}_{\{Y_t \in A\}}) \\
 = & t \sum_{n=0}^{\infty} \frac{e^{-\lambda t} (\lambda t)^n}{n!} (P(X_1 + \dots + X_{n+1} \in A) - P(X_1 + \dots + X_n \in A)) \\
 = & t E\left(\sum_{n=0}^{\infty} \frac{e^{-\lambda t} (\lambda t)^n}{n!} (P(X_1 + \dots + X_n + x \in A) - P(X_1 + \dots + X_n \in A))\right)_{x=x} \\
 = & E \int_0^T E(\Psi_{s,x}(\mathbf{1}_{\{Y_t \in A\}}))_{x=x} ds = E \int_{\mathbb{R}} \int_0^T \Psi_{s,x}(\mathbf{1}_{\{Y_t \in A\}}) f(x) dx ds,
 \end{aligned}$$

where $\Psi_{s,x}(\mathbf{1}_{\{Y_t(\omega) \in A\}}) = \mathbf{1}_{\{Y_t(\omega_{s,x}) \in A\}} - \mathbf{1}_{\{Y_t(\omega) \in A\}}$, where $\omega_{s,x}$ is a trajectory like ω but where we add a jump with amplitude x at time s .

We also can write

$$\partial_\lambda E(\mathbf{1}_{\{Y_t \in A\}}) = \frac{1}{\lambda} E\left(\int_{\mathbb{R}} \int_0^T \Psi_{s,x}(\mathbf{1}_{\{Y_t \in A\}}) \nu(dx) ds\right),$$

where $\nu(dx) = \lambda f(x) dx$ is the Lévy measure of the compound Poisson process Y .

If we denote by δ the adjoint operator of $\Psi_{\cdot, \cdot}$, we deduce from the previous calculations that the score function can be written as

$$E \left(\delta \left(\frac{1}{\lambda} \right) \mid Y_{t_1}, \dots, Y_{t_n} \right)$$

Let $L_i := Y_{t_i} - Y_{t_{i-1}} = \int_{t_{i-1}}^{t_i} \int_{\mathbb{R}} g(\theta, x) M(dx, ds)$, $i = 1, \dots, n$, with

$$M(dx, ds) = \sum_{k=1}^{\infty} \delta_{\{\tau_k\}}(ds) \delta_{\{X_k\}}(dx),$$

where $0 < \tau_1 < \tau_2 < \dots < \tau_n$ is a sequence of jump times of a Poisson process with intensity one and $X_i, i = 1, \dots, n, \dots$ is an iid sequence independent of $(\tau_i)_{i \geq 1}$ and with density f , $g(\theta, x)$ is a deterministic function. Note that there is not change in the intensity of the Lévy process but in the amplitude of the jumps.

In such a situation we have

$$\partial_{\theta} E(T) = \sum_{j=1}^n E(\partial_{Y_j} T \partial_{\theta} L_j),$$

and

$$\begin{aligned} \partial_{\theta} L_j &= \int_{t_{j-1}}^{t_j} \int_{\mathbb{R}} \partial_{\theta} g(\theta, x) M(dx, ds) \\ &= \sum_{k=1}^{\infty} \partial_{\theta} g(\theta, X_k) \mathbf{1}_{(\tau_k \in (t_{j-1}, t_j])}, \end{aligned}$$

Then we can write

$$\begin{aligned}
 \partial_{\theta} E(T(Y)) &= \sum_{j=1}^n \sum_{k=1}^{\infty} E(\partial_{L_j} T \partial_{X_k} L_j \partial_{\theta} g(\theta, X_k) \frac{1}{\partial_x g(\theta, X_k)} \mathbf{1}_{(\tau_k \in (t_{j-1}, t_j])}) \\
 &= \sum_{j=1}^n \sum_{k=1}^{\infty} E(\partial_{X_k} T \frac{\partial_{\theta} g(\theta, X_k)}{\partial_x g(\theta, X_k)} \mathbf{1}_{(\tau_k \in (t_{j-1}, t_j])}) \\
 &= - \sum_{j=1}^n \sum_{k=1}^{\infty} E \left(T \frac{1}{f(X_k)} \partial_x \left(\frac{\partial_{\theta} g(\theta, x) f(x)}{\partial_x g(\theta, x)} \right)_{x=X_k} \mathbf{1}_{(\tau_k \in (t_{j-1}, t_j])} \right),
 \end{aligned}$$

where in the last equality we use the independence between (X_k) and the jump times and where we assume there are not "border" effects .

Finally

$$\begin{aligned}
 \partial_{\theta} E(T) &= - \sum_{j=1}^n \sum_{k=1}^{\infty} E \left(T \frac{1}{f(X_k)} \partial_x \left(\frac{\partial_{\theta} g(\theta, x) f(x)}{\partial_x g(\theta, x)} \right)_{x=X_k} \mathbf{1}_{(\tau_k \in (t_{j-1}, t_j])} \right) \\
 &= - E \left(T \sum_{j=1}^n \int_{\mathbb{R}} \int_{t_{j-1}}^{t_j} \frac{1}{f(x)} \partial_x \left(\frac{\partial_{\theta} g(\theta, x) f(x)}{\partial_x g(\theta, x)} \right) M(dx, ds) \right) \\
 &= - E \left(T \int_{\mathbb{R}} \int_{t_0}^{t_n} \frac{1}{f(x)} \partial_x \left(\frac{\partial_{\theta} g(\theta, x) f(x)}{\partial_x g(\theta, x)} \right) M(dx, ds) \right).
 \end{aligned}$$

So, the score function is given by

$$- E \left(\int_{\mathbb{R}} \int_{t_0}^{t_n} \frac{1}{f(x)} \partial_x \left(\frac{\partial_{\theta} g(\theta, x) f(x)}{\partial_x g(\theta, x)} \right) M(dx, ds) \mid Y_1, Y_2, \dots, Y_n \right).$$

CLT. Random variables in a fixed chaos

Theorem

Fix $n \geq 2$. Consider a sequence $\{F_k = I_n(f_k), k \geq 1\}$ such that

$$E(F_k^2) \xrightarrow[k \rightarrow \infty]{} \sigma^2 \quad (3)$$

The following statements are equivalent:

(i) $F_k \xrightarrow[k \rightarrow \infty]{\mathcal{L}} N(0, \sigma^2)$.

(ii) $E(F_k^4) \xrightarrow[k \rightarrow \infty]{} 3\sigma^4$.

(iii) $\|f_k \otimes_r f_k\|_{\mathfrak{H}^{\otimes 2(n-r)}} \xrightarrow[k \rightarrow \infty]{} 0$, for all $1 \leq r \leq n-1$.

(iv) $\|DF_k\|_{\mathfrak{H}}^2 \xrightarrow[k \rightarrow \infty]{L^2(\Omega)} n\sigma^2$.

CLT. Random variables in a fixed chaos

Example

Consider a sequence of stationary, normalized, centered Gaussian random variables $(X_i)_{i \geq 1}$. We want to study the asymptotic behavior of the sequence

$$F_k := \frac{1}{\sqrt{k}} \sum_{i=1}^k H_m(X_i),$$

$m \geq 2$. We can take $\mathcal{H}_1 = \text{span}\{X_i, i \geq 1\}$, and $\mathfrak{H} \equiv \mathcal{H}_1$. The inner product on \mathfrak{H} is then induced by the covariance function $\rho(k) = \text{cov}(X_1, X_{1+k})$ of the sequence $(X_i)_{i \geq 1}$ (note that $\rho(0) = 1$). We obtain the following representation

$$F_k = \frac{1}{\sqrt{k}} \sum_{i=1}^k H_m(X_i) = I_m \left(\frac{1}{\sqrt{k}} \sum_{i=1}^k X_i^{\otimes m} \right).$$

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CLT. Random vectors with components in fixed chaos

For $d \geq 2$, fix d natural numbers, $1 \leq n_1 \leq \dots \leq n_d$. Consider a sequence of random vectors

$$F_k = (F_k^1, \dots, F_k^d) = (I_{n_1}(f_k^1), \dots, I_{n_d}(f_k^d)), \quad (4)$$

where $f_k^i \in \mathfrak{H}^{\odot n_i}$. We have a multidimensional version of the previous theorem,

CLT. Random vectors with components in fixed chaos

Theorem

Let $(F_k)_{k \geq 1}$ be a sequence of random vectors of the form (4) such that, for every $1 \leq i, j \leq d$

$$\lim E(F_k^i F_k^j) = \delta_{ij}, \quad (5)$$

then the following statements are equivalent

(i) For every $i = 1, \dots, d$, $F_k^i \xrightarrow[k \rightarrow \infty]{\mathcal{L}} N(0, 1)$.

(ii) For every $i = 1, \dots, d$, $E\left(\left(F_k^i\right)^4\right) \xrightarrow[k \rightarrow \infty]{} 3$.

(iii) $\left\| f_k^i \otimes_r f_k^i \right\|_{\mathfrak{H}^{\otimes 2(n_i-r)}} \xrightarrow[k \rightarrow \infty]{} 0$, for all $1 \leq r \leq n_i - 1, 1 \leq i \leq d$.

(iv) For every $i = 1, \dots, d$, $\left\| DF_k^i \right\|_{\mathfrak{H}}^2 \xrightarrow[k \rightarrow \infty]{L^2(\Omega)} n_i$.

(v) $F_k \xrightarrow[k \rightarrow \infty]{\mathcal{L}} N_d(0, I_d)$

Finally, we can consider a d -dimensional random vector $F_k = (Y_k^1, \dots, Y_k^d)^T$ which has a chaos representation

$$F_k^i = \sum_{m=1}^{\infty} I_m(f_{m,k}^i), \quad i = 1, \dots, d,$$

with $f_{m,k}^i \in \mathfrak{H}^{\odot m}$.

Theorem

Suppose that the following conditions hold:

- (i) For any $i = 1, \dots, d$ we have $\sum_{m=1}^{\infty} \sup_k m! \|f_{m,k}^i\|_{\mathcal{H}^{\otimes m}}^2 < \infty$.
- (ii) For any $m \geq 1, i, j = 1, \dots, d$ we have constants Σ_{ij}^m such that

$$\lim_{k \rightarrow \infty} E[I_m(f_{m,k}^i) I_m(f_{m,k}^j)] = \lim_{k \rightarrow \infty} \langle f_{m,k}^i, f_{m,k}^j \rangle_{\mathcal{H}^{\otimes m}} = \Sigma_{ij}^m,$$

and the matrix $\Sigma^m = (\Sigma_{ij}^m)_{1 \leq i, j \leq d}$ is positive definite for all m .

- (iii) $\sum_{m=1}^{\infty} \Sigma^m = \Sigma \in \mathbb{R}^{d \times d}$.
- (iv) For any $m \geq 1, i = 1, \dots, d$ and $p = 1, \dots, m-1$

$$\lim_{k \rightarrow \infty} \|f_{m,k}^i \otimes_p f_{m,k}^i\|_{\mathcal{H}^{\otimes 2(m-p)}}^2 = 0.$$

Then we have $F_k \xrightarrow[k \rightarrow \infty]{\mathcal{L}} N_d(0, \Sigma)$.

Let $(G_t)_{t \geq 0}$ be a Gaussian process which has centered and stationary increments. We want to study the asymptotic properties of the process

$$V(G, \rho)_t^n = \frac{1}{n\tau_n^\rho} \sum_{i=1}^{[nt]} |\Delta_i^n G|^\rho,$$

where $\Delta_i^n G = G_{\frac{i}{n}} - G_{\frac{i-1}{n}}$, $\tau_n^2 = E[|\Delta_1^n G|^2]$ and $\rho > 0$. Write

$$r_n(j) = \text{Cov}\left(\frac{\Delta_1^n G}{\tau_n}, \frac{\Delta_{1+j}^n G}{\tau_n}\right), \quad j \geq 0.$$

and assume that

$$|r_n(j)|^2 \leq Cj^{-1-\varepsilon}, \quad j \geq 0, \text{ for some } \varepsilon > 0 \quad (6)$$

and

$$\lim_{n \rightarrow \infty} r_n(j) = \rho(j),$$

Set $H(x) = |x|^\rho - \mu_\rho$, where $\mu_\rho = E(|N(0, 1)|^\rho)$, then $H(x) = \sum_{j=2}^{\infty} a_j H_j(x)$, with $a_2 > 0$ and we have the following theorem:

Theorem

$$\left(G_t, \sqrt{n}(V(G, p)_t^n - t\mu_p) \right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \left(G_t, \sigma W_t \right),$$

where W is a Brownian motion that is defined on an extension of the filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, P)$, independent of G and σ^2 is given by

$$\sigma^2 = \sum_{m=2}^{\infty} \sigma_m^2, \quad \sigma_m^2 = m! a_m^2 \lambda_m^2, \quad \lambda_m^2 = 1 + 2 \sum_{i=1}^{\infty} \rho^m(i). \quad (7)$$

Let \mathcal{H}_1 the closed subspace of $L^2(\Omega, \mathcal{F}, P)$ generated by the random variables $(\Delta_j^n G / \tau_n)_{n \geq 1, 1 \leq j \leq [nT]}$. Notice that \mathcal{H}_1 is a separable Hilbert space with the scalar product induced by the covariance function of the triangular array $(\Delta_j^n G / \tau_n)_{n \geq 1, 1 \leq j \leq [nT]}$. Then we can take $\mathfrak{H} = \mathcal{H}_1$ and try to apply the general CLT to this case.

We can also study with similar tools the multipower variation

$$V(G, p_1, \dots, p_k)_t^n = \frac{1}{n} \sum_{i=1}^{[nt]-k+1} \prod_{j=1}^k \left| \frac{\Delta_{i+j-1}^n G}{\tau_n} \right|^{p_j}, \quad p_1, \dots, p_k \geq 0,$$

and for the **joint** multipower variation:

$$\left(V(G, p_1^1, \dots, p_k^1)_t^n, \dots, V(G, p_1^d, \dots, p_k^d)_t^n \right).$$

Define

$$\rho_{p_1, \dots, p_k}^{(n)} = E \left[\left| \frac{\Delta_1^n G}{\tau_n} \right|^{p_1} \dots \left| \frac{\Delta_k^n G}{\tau_n} \right|^{p_k} \right].$$

We have






Theorem






$$\left(G_t, \sqrt{n} \left(V(p_1^j, \dots, p_k^j)_t^n - \rho_{p_1^j, \dots, p_k^j}^{(n)} t \right)_{1 \leq j \leq d} \right) \rightarrow (G_t, \beta^{1/2} W_t),$$

where W is a d -dimensional Brownian, defined in an extension of the original filtered space, independent of G , β is a $d \times d$ -dimensional matrix given by

$$\beta_{ij} = \lim_{n \rightarrow \infty} n \operatorname{cov} \left(V_Q(p_1^i, \dots, p_k^i)_1^n, V_Q(p_1^j, \dots, p_k^j)_1^n \right), \quad 1 \leq i, j \leq d,$$

and $(Q_i)_{i \geq 1}$ is stationary centered discrete time Gaussian process with correlation function $\rho(j)$.

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