

Infinite IFS: limit sets and continuity

Martial Hille

HU Berlin

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Outline of the talk

- 1 Motivation
- 2 Definition of different limit sets
- 3 Some results on limit sets
- 4 Set of accumulation points and relations to limit sets

Based on the recent preprints

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- 5 The space of self similar IFSs
- 6 Metric on the space of s.s. IFSs
- 7 Continuity results

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- 7 Continuity results
- 8 Future prospects

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Motivation: Finite vs. infinite IFS

Let $S := \{S_i \mid i \in I\}$ satisfy OSC, I **finite**, then $\exists!$ compact $K \neq \emptyset$ s.t.

$$K = \bigcup_{i \in I} S_i(K), \quad \text{and we have } K = \pi(I^\infty).$$

If I is infinite, this generalises to two different sets, namely the invariant set

$$\pi(I^\infty) = \bigcup_{i \in I} S_i(\pi(I^\infty)),$$

and the closed set

$$\overline{\pi(I^\infty)}.$$

Different limit sets

Definition

Let $\mathbf{S} = \{S_i : X \rightarrow X \mid i \in I := \mathbb{N}\}$ be an infinite IFS acting on a compact set $X \subset \mathbb{R}^m$, with $X = \overline{\text{Int}(X)}$ which satisfies OSC.

We then define the following types of limit sets of \mathbf{S} .

- The *dynamical limit set* $L_{\text{dyn}}(\mathbf{S}) := \pi(I^\infty)$.
- The *limit set* $L(\mathbf{S}) := \overline{L_{\text{dyn}}(\mathbf{S})}$.
- The *Jørgensen limit set* $L_J(\mathbf{S}) := L(\mathbf{S}) \setminus L_{\text{dyn}}(\mathbf{S})$.

Question

What is the relation between $\dim_{\text{H}} L_J(\mathbf{S})$ and $\dim_{\text{H}} L_{\text{dyn}}(\mathbf{S})$?

Some answers

Theorem (Moran '95/ Mauldin-Urbanski'96)

For all self-similar infinite IFS

$$\dim_{\text{H}} L_{\text{dyn}}(\mathbf{S}) = \inf\{s > 0 \mid \sum_{i \in I} r_i^s \leq 1\}.$$

Theorem (H.)

For every $m \in \mathbb{N}$ and $d, j \in (0, m)$ there exists an infinite (self-similar) IFS \mathbf{S} acting on \mathbb{R}^m such that

$$\dim_{\text{H}} L_{\text{dyn}}(\mathbf{S}) = d \quad \text{and} \quad \dim_{\text{H}} L_{\text{J}}(\mathbf{S}) = j.$$

(Moreover, \mathbf{S} is regular and satisfies SSC.)

Set of accumulation points and limit sets

Definition of the set of accumulation points

$$\text{Acc}(\mathbf{S}) := \bigcup_{J \subset I} \left(\overline{\bigcup_{i \in J} S_i(X)} \setminus \bigcup_{i \in J} S_i(X) \right)$$

Some relations to limit sets

We have

$$L_J(\mathbf{S}) \subset \mathcal{O}_{\mathbf{S}}(\text{Acc}(\mathbf{S})) \quad \text{and} \quad \text{Acc}(\mathbf{S}) \subset L(\mathbf{S})$$

and hence

$$\begin{aligned} \dim_{\text{H}} L(\mathbf{S}) &= \max\{\dim_{\text{H}} L_{\text{dyn}}(\mathbf{S}), \dim_{\text{H}} L_J(\mathbf{S})\} \\ &= \max\{\dim_{\text{H}} L_{\text{dyn}}(\mathbf{S}), \dim_{\text{H}} \text{Acc}(\mathbf{S})\}. \end{aligned}$$

A priori conditions for $\mathcal{O}_{\mathbf{S}}(\text{Acc}(\mathbf{S})) = \text{L}_J(\mathbf{S})$.

Theorem (H.)

Let \mathbf{S} satisfy OSC.

$$\text{If } \exists \bar{U} \subset \text{Int } X \quad \text{s.t.} \quad S_i(X) \subset \bar{U}, \quad \forall i \in I,$$

then

$$\mathcal{O}_{\mathbf{S}}(\text{Acc}(\mathbf{S})) = \text{L}_J(\mathbf{S}).$$

Theorem (H. - one dimensional systems)

If \mathbf{S} satisfies OSC and if $X \subset \mathbb{R}$ consists of finitely many intervals, then

$$\dim_{\text{H}} \text{L}_J(\mathbf{S}) = \dim_{\text{H}} \text{Acc}(\mathbf{S}).$$

The space of s.s. IFSs (joint work with N.Snigireva [HS])

If \mathbf{S} satisfies SSC then \mathbf{S} satisfies OSC, but how does the space of IFS look like?

A first answer: Fix $I \subset \mathbb{N}$ and $X \subset \mathbb{R}^m$ as above. Then define

$$\text{IFS}(X, I) := \{\mathbf{S} = \{S_i : X \rightarrow X \mid i \in I\}, \mathbf{S} \text{ satisfies OSC}\},$$

$$\text{IFS}_{\text{SSC}}(X, I) := \{\mathbf{S} \in \text{IFS}(X, I), \mathbf{S} \text{ satisfies SSC}\},$$

$$\text{IFS}_{\text{OSC}}(X, I) := \text{IFS}(X, I) \setminus \text{IFS}_{\text{SSC}}(X, I).$$

Theorem (H.S.)

Under certain conditions on X we have

$$\text{IFS}_{\text{SSC}}(X, I) = \text{Int } \text{IFS}(X, I).$$

$$\text{IFS}_{\text{OSC}}(X, I) \subsetneq \partial \text{IFS}(X, I).$$

$\partial \text{IFS}(X, I)$ also contains inhomogeneous IFS, as well as pathological systems.

Parameter space of IFS(X, I) [HS]

Parametrisation

Each similarity S_i is of the form

$$S_i : x \mapsto r_i \cdot O_i(x) + b_i \quad \text{with} \quad \begin{array}{l} r_i \in (0, 1), \\ O_i \in O(m) \subset GL(m), \\ b_i \in \mathbb{R}^m. \end{array}$$

With this identification $S_i \in (0, 1) \times \mathbb{R}^m \times O(m)$.

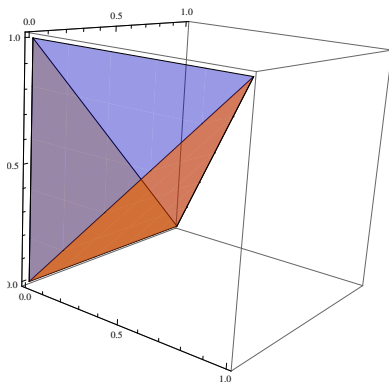
Parameter space of IFS(X, I)

Each $\mathbf{S} \in \text{IFS}(X, I)$ can be identified with an element in

$$((0, 1) \times \mathbb{R}^m \times O(m))^I.$$

Example of IFS($[0, 1]$, $\{1, 2\}$) [HS]

Let $X := [0, 1]$, $I := \{1, 2\}$ and fix $O_1 = O_2 = 1$ and fix $b_1 = 0$.



Metric on parameter space of s.s. IFS [HS]

On the space of similarities

$$\{S_i \in (0, 1) \times \mathbb{R}^m \times O(m)\}$$

we define a metric d by

$$d(f_1, f_2) := |\log r_1 - \log r_2| + \|b_1 - b_2\| + d(O_1, O_2).$$

d extends to an extended metric on $\text{IFS}(X, I)$ by

$$d_{\text{ex}}(\mathbf{S}, \mathbf{T}) := \sum_{i \in I} d(S_i, T_i) \in [0, \infty].$$

$$d(\mathbf{S}, \mathbf{T}) := \frac{d_{\text{ex}}(\mathbf{S}, \mathbf{T})}{1 + d_{\text{ex}}(\mathbf{S}, \mathbf{T})} \text{ is now a metric.}$$

Continuity results [HS]

Theorem (Continuity (H.S.))

The following maps are continuous w.r.t. d . (and $d_{\text{Hausdorff}}$) :

$$\begin{array}{ll} \mathbf{S} \mapsto \dim_{\mathbb{H}} L(\mathbf{S}), & \mathbf{S} \mapsto \dim_{\mathbb{H}} L_{\text{dyn}}(\mathbf{S}) \\ \mathbf{S} \mapsto L(\mathbf{S}), & \mathbf{S} \mapsto L_{\text{dyn}}(\mathbf{S}), \\ \mathbf{S} \mapsto \text{Acc}(\mathbf{S}) & \text{(even locally constant).} \end{array}$$

If $X \subset \mathbb{R}$ consists of finitely many intervals, then the map

$$\mathbf{S} \mapsto \dim_{\mathbb{H}} L_J(\mathbf{S}) \quad \textit{is continuous w.r.t. } d.$$

Theorem (Discontinuity (H.S.))

The maps $\mathbf{S} \mapsto L_J(\mathbf{S})$ and $\mathbf{S} \mapsto \dim_{\mathbb{H}} L_J(\mathbf{S})$ are in general not continuous.

Future prospects

- (i) Continuity results for conformal \mathbf{S} under (certain) deformations of the seed space X .
- (ii) Relation to the modular space of $\text{IFS}(X, I)$.
- (iii) Generalisation to (pseudo) graph directed Markov systems.

Thank you!

This talk was based on:

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