

Matrix Completion and Matrix Concentration

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Part I

Divide-Factor-Combine

Motivation: Large-scale Matrix Completion

Goal: Estimate a matrix $\mathbf{L}_0 \in \mathbb{R}^{m \times n}$ given a subset of its entries

$$\begin{bmatrix} ? & ? & 1 & \dots & 4 \\ 3 & ? & ? & \dots & ? \\ ? & 5 & ? & \dots & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 3 & 1 & \dots & 4 \\ 3 & 4 & 5 & \dots & 1 \\ 2 & 5 & 3 & \dots & 5 \end{bmatrix}$$

Examples

- Collaborative filtering: How will user i rate movie j ?
 - Netflix: 10 million users, 100K DVD titles
- Ranking on the web: Is URL j relevant to user i ?
 - Google News: millions of articles, millions of users
- Link prediction: Is user i friends with user j ?
 - Facebook: 500 million users

Motivation: Large-scale Matrix Completion

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State of the art MC algorithms

- Strong estimation guarantees
- Plagued by expensive subroutines (e.g., truncated SVD)

This talk

- Present divide and conquer approaches for **scaling up** any MC algorithm while **maintaining strong estimation guarantees**

Exact Matrix Completion

Goal: Estimate a matrix $\mathbf{L}_0 \in \mathbb{R}^{m \times n}$ given a subset of its entries

Noisy Matrix Completion

Goal: Given entries from a matrix $\mathbf{M} = \mathbf{L}_0 + \mathbf{Z} \in \mathbb{R}^{m \times n}$ where \mathbf{Z} is entrywise noise and \mathbf{L}_0 has rank $r \ll m, n$, estimate \mathbf{L}_0

- **Good news:** \mathbf{L}_0 has $\sim (m+n)r \ll mn$ degrees of freedom

$$\mathbf{L}_0 = \mathbf{A} \mathbf{B}^T$$

- Factored form: $\mathbf{A} \mathbf{B}^T$ for $\mathbf{A} \in \mathbb{R}^{m \times r}$ and $\mathbf{B} \in \mathbb{R}^{n \times r}$
- **Bad news:** Not all low-rank matrices can be recovered

Question: What can go wrong?

What can go wrong?

Entire column missing

$$\begin{bmatrix} 1 & 2 & ? & 3 & \dots & 4 \\ 3 & 5 & ? & 4 & \dots & 1 \\ 2 & 5 & ? & 2 & \dots & 5 \end{bmatrix}$$

- No hope of recovery!

Solution: Uniform observation model

Assume that the set of s observed entries Ω is drawn uniformly at random:

$$\Omega \sim \text{Unif}(m, n, s)$$

What can go wrong?

Bad spread of information

$$\mathbf{L} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} [1] [1 \ 0 \ 0] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

- Can only recover \mathbf{L} if \mathbf{L}_{11} is observed

Solution: Incoherence with standard basis (Candès and Recht, 2009)

A matrix $\mathbf{L} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^\top \in \mathbb{R}^{m \times n}$ with $\text{rank}(\mathbf{L}) = r$ is (μ, r) -coherent if

Singular vectors are **not too sparse**: $\begin{cases} \max_i \|\mathbf{U}\mathbf{U}^\top \mathbf{e}_i\|^2 \leq \mu r / m \\ \max_i \|\mathbf{V}\mathbf{V}^\top \mathbf{e}_i\|^2 \leq \mu r / n \end{cases}$

and **not too cross-correlated**: $\|\mathbf{U}\mathbf{V}^\top\|_\infty \leq \sqrt{\frac{\mu r}{mn}}$

How do we estimate \mathbf{L}_0 ?

First attempt:

$$\begin{aligned} & \text{minimize}_{\mathbf{A}} \quad \text{rank}(\mathbf{A}) \\ & \text{subject to} \quad \sum_{(i,j) \in \Omega} (\mathbf{A}_{ij} - \mathbf{M}_{ij})^2 \leq \Delta^2. \end{aligned}$$

Problem: Intractable to solve!

Solution: Solve **convex** relaxation (Fazel, Hindi, and Boyd, 2001; Candès and Plan, 2010)

$$\begin{aligned} & \text{minimize}_{\mathbf{A}} \quad \|\mathbf{A}\|_* \\ & \text{subject to} \quad \sum_{(i,j) \in \Omega} (\mathbf{A}_{ij} - \mathbf{M}_{ij})^2 \leq \Delta^2 \end{aligned}$$

where $\|\mathbf{A}\|_* = \sum_k \sigma_k(\mathbf{A})$ is the trace/nuclear norm of \mathbf{A} .

Questions:

- Will the nuclear norm heuristic successfully recover \mathbf{L}_0 ?
- Can nuclear norm minimization scale to large MC problems?

Noisy Nuclear Norm Heuristic: Does it work?

Yes, with high probability.

Typical Theorem

If \mathbf{L}_0 is (μ, r) -coherent, $s = O(\mu rn \log^2(n))$ entries of $\mathbf{M} \in \mathbb{R}^{m \times n}$ are observed uniformly at random, and $\hat{\mathbf{L}}$ solves the noisy nuclear norm heuristic, then

$$\|\hat{\mathbf{L}} - \mathbf{L}_0\|_F \leq f(m, n)\Delta$$

with high probability when $\|\mathbf{M} - \mathbf{L}_0\|_F \leq \Delta$.

- See Candès and Plan (2010); Mackey, Talwalkar, and Jordan (2011); Keshavan, Montanari, and Oh (2010); Negahban and Wainwright (2010)
- Implies **exact** recovery in the noiseless setting ($\Delta = 0$)

Noisy Nuclear Norm Heuristic: Does it scale?

Not quite...

- Standard interior point methods (Candès and Recht, 2009):
 $O(|\Omega|(m+n)^3 + |\Omega|^2(m+n)^2 + |\Omega|^3)$
- More efficient, tailored algorithms:
 - Singular Value Thresholding (SVT) (Cai, Candès, and Shen, 2010)
 - Augmented Lagrange Multiplier (ALM) (Lin, Chen, Wu, and Ma, 2009)
 - Accelerated Proximal Gradient (APG) (Toh and Yun, 2010)
 - All require rank- k truncated SVD on **every** iteration

Take away: Provably accurate MC algorithms are still **too expensive** for large-scale or real-time matrix completion

Question: How can we **scale up** a given matrix completion algorithm and still **retain estimation guarantees**?

Divide-Factor-Combine (DFC)

Our Solution: Divide and conquer

- 1 Divide M into submatrices.
- 2 Factor each submatrix **in parallel**.
- 3 Combine submatrix estimates to estimate L_0 .

Advantages

- Factoring a submatrix is often much cheaper than factoring M
- Multiple submatrix factorizations can be carried out in parallel
- DFC works with **any** base MC algorithm
- With the right choice of division and recombination, yields estimation guarantees comparable to those of the base algorithm

DFC-PROJ: Partition and Project

- ① Randomly partition \mathbf{M} into n/l column submatrices $\mathbf{M} = [\mathbf{C}_1 \ \mathbf{C}_2 \ \cdots \ \mathbf{C}_{n/l}]$ where each $\mathbf{C}_i \in \mathbb{R}^{m \times l}$

- ② Complete the submatrices **in parallel** to obtain

$$[\hat{\mathbf{C}}_1 \ \hat{\mathbf{C}}_2 \ \cdots \ \hat{\mathbf{C}}_{n/l}]$$

- **Reduced cost:** Expect $\min(n/l, m/d)$ speed-up per iteration
- **Parallel computation:** Pay cost of one cheaper MC

- ③ Recover a single factorization for \mathbf{M} by projecting each submatrix onto the column space of $\hat{\mathbf{C}}_1$

$$\hat{\mathbf{L}}^{proj} = \hat{\mathbf{C}}_1 \hat{\mathbf{C}}_1^+ [\hat{\mathbf{C}}_1 \ \hat{\mathbf{C}}_2 \ \cdots \ \hat{\mathbf{C}}_{n/l}]$$

- **Minimal cost:** $O(mk^2 + lk^2)$ where $k = \text{rank}(\hat{\mathbf{L}}^{proj})$

- ④ **Ensemble:** Project onto column space of each $\hat{\mathbf{C}}_j$ and average

DFC: Does it work?

Yes, with high probability.

Theorem (Mackey, Talwalkar, and Jordan, 2011)

If \mathbf{L}_0 is (μ, r) -coherent and s entries of $\mathbf{M} \in \mathbb{R}^{m \times n}$ are observed uniformly at random, then

$$l = O\left(\frac{\mu^2 r^2 n^2 \log^2(n)}{s \epsilon^2}\right)$$

random columns suffice to have

$$\|\hat{\mathbf{L}}^{proj} - \mathbf{L}_0\|_F \leq (2 + \epsilon) f(m, n) \Delta$$

with high probability when $\|\mathbf{M} - \mathbf{L}_0\|_F \leq \Delta$ and the noisy nuclear norm heuristic is used as a base algorithm.

- Can sample vanishingly small fraction of columns ($l/n \rightarrow 0$) whenever $s = \omega(n \log^2(n))$
- Implies exact recovery for noiseless ($\Delta = 0$) setting

DFC: Does it work?

Yes, with high probability.

Proof Ideas:

- 1 Uniform column/row sampling yields **submatrices with low coherence** (high spread of information) w.h.p.
 - 2 Each submatrix has **sufficiently many observed entries** w.h.p.
⇒ Submatrix completion succeeds
 - 3 Uniform sampling of columns/rows **captures the full column/row space** of \mathbf{L}_0 w.h.p.
 - Noisy analysis builds on randomized ℓ_2 regression work of Drineas, Mahoney, and Muthukrishnan (2008)
- ⇒ Column projection succeeds

DFC Noisy Recovery Error

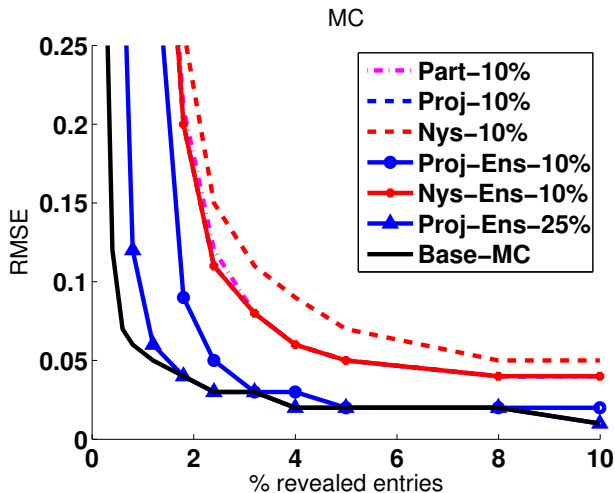


Figure: Recovery error of DFC relative to base algorithms with $(m = 10K, r = 10)$.

DFC Speed-up

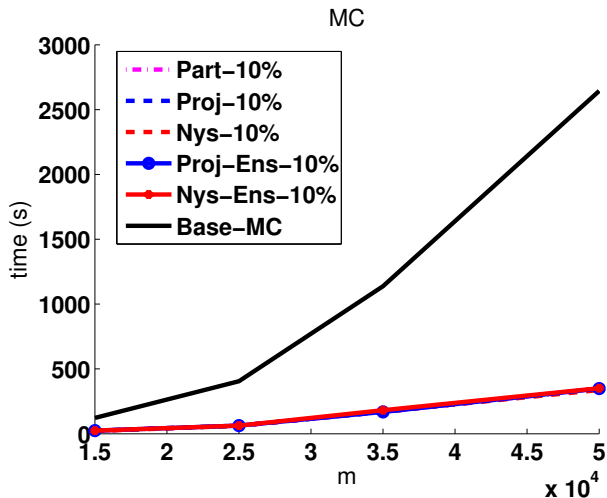


Figure: Speed-up over APG for random matrices with $r = 0.001m$ and 4% of entries revealed.

Application: Collaborative filtering

Task: Given a sparsely observed matrix of user-item ratings, predict the unobserved ratings

Issues

- Full-rank rating matrix
- Noisy, non-uniform observations

The Data

- **Netflix Prize Dataset**¹
 - 100 million ratings in $\{1, \dots, 5\}$
 - 17,770 movies, 480,189 users

¹<http://www.netflixprize.com/>

Application: Collaborative filtering

Method	Netflix	
	RMSE	Time
APG	0.8433	2653.1s
DFC-PROJ-25%	0.8436	689.5s
DFC-PROJ-10%	0.8484	289.7s
DFC-PROJ-ENS-25%	0.8411	689.5s
DFC-PROJ-ENS-10%	0.8433	289.7s

Part II

Stein's Method for Matrix Concentration Inequalities

Concentration Inequalities

Matrix concentration

$$\mathbb{P}\{\|\mathbf{X} - \mathbb{E} \mathbf{X}\| \geq t\} \leq \delta$$

$$\mathbb{P}\{\lambda_{\max}(\mathbf{X} - \mathbb{E} \mathbf{X}) \geq t\} \leq \delta$$

- Non-asymptotic control of random matrices with complex distributions

Applications

- Matrix estimation from sparse random measurements
(Gross, 2011; Recht, 2009; Mackey, Talwalkar, and Jordan, 2011)
- Randomized matrix multiplication and factorization
(Drineas, Mahoney, and Muthukrishnan, 2008; Hsu, Kakade, and Zhang, 2011b)
- Convex relaxation of robust or chance-constrained optimization
(Nemirovski, 2007; So, 2011; Cheung, So, and Wang, 2011)
- Random graph analysis (Christofides and Markström, 2008; Oliveira, 2009)

Concentration Inequalities

Matrix concentration

$$\mathbb{P}\{\lambda_{\max}(\mathbf{X} - \mathbb{E} \mathbf{X}) \geq t\} \leq \delta$$

Difficulty: Matrix multiplication is not commutative

Past approaches (Oliveira, 2009; Tropp, 2011; Hsu, Kakade, and Zhang, 2011a)

- Deep results from matrix analysis
- Sums of independent matrices and matrix martingales

This work

- Stein's method of exchangeable pairs (1972), as advanced by Chatterjee (2007) for scalar concentration
 - ⇒ Improved exponential tail inequalities (Hoeffding, Bernstein)
 - ⇒ Polynomial moment inequalities (Khintchine, Rosenthal)
 - ⇒ Dependent sums and more general matrix functionals

Roadmap

- 3 Motivation
- 4 Stein's Method Background and Notation
- 5 Exponential Tail Inequalities
- 6 Polynomial Moment Inequalities
- 7 Extensions

Notation

Hermitian matrices: $\mathbb{H}^d = \{\mathbf{A} \in \mathbb{C}^{d \times d} : \mathbf{A} = \mathbf{A}^*\}$

- *All matrices in this talk are Hermitian.*

Maximum eigenvalue: $\lambda_{\max}(\cdot)$

Trace: $\text{tr } \mathbf{B}$, the sum of the diagonal entries of \mathbf{B}

Spectral norm: $\|\mathbf{B}\|$, the maximum singular value of \mathbf{B}

Schatten p -norm: $\|\mathbf{B}\|_p := (\text{tr}|\mathbf{B}|^p)^{1/p}$ for $p \geq 1$

Matrix Stein Pair

Definition (Exchangeable Pair)

(Z, Z') is an *exchangeable pair* if $(Z, Z') \stackrel{d}{=} (Z', Z)$.

Definition (Matrix Stein Pair)

Let (Z, Z') be an auxiliary exchangeable pair, and let $\Psi : \mathcal{Z} \rightarrow \mathbb{H}^d$ be a measurable function. Define the random matrices

$$\mathbf{X} := \Psi(Z) \quad \text{and} \quad \mathbf{X}' := \Psi(Z').$$

$(\mathbf{X}, \mathbf{X}')$ is a *matrix Stein pair* with scale factor $\alpha \in (0, 1]$ if

$$\mathbb{E}[\mathbf{X}' \mid Z] = (1 - \alpha)\mathbf{X}.$$

- Matrix Stein pairs are exchangeable pairs
- Matrix Stein pairs always have zero mean

The Conditional Variance

Definition (Conditional Variance)

Suppose that $(\mathbf{X}, \mathbf{X}')$ is a matrix Stein pair with scale factor α , constructed from the exchangeable pair (Z, Z') . The *conditional variance* is the random matrix

$$\Delta_{\mathbf{X}} := \Delta_{\mathbf{X}}(Z) := \frac{1}{2\alpha} \mathbb{E} [(\mathbf{X} - \mathbf{X}')^2 | Z].$$

- $\Delta_{\mathbf{X}}$ is a stochastic estimate for the variance, $\mathbb{E} \mathbf{X}^2$
- Control over $\Delta_{\mathbf{X}}$ yields control over $\lambda_{\max}(\mathbf{X})$

Exponential Concentration for Random Matrices

Theorem (Mackey, Jordan, Chen, Farrell, and Tropp, 2012)

Let $(\mathbf{X}, \mathbf{X}')$ be a matrix Stein pair with $\mathbf{X} \in \mathbb{H}^d$. Suppose that

$$\Delta_{\mathbf{X}} \preceq c\mathbf{X} + v\mathbf{I} \quad \text{almost surely for } c, v \geq 0.$$

Then, for all $t \geq 0$,

$$\mathbb{P}\{\lambda_{\max}(\mathbf{X}) \geq t\} \leq d \cdot \exp\left\{\frac{-t^2}{2v + 2ct}\right\}.$$

- Control over the conditional variance $\Delta_{\mathbf{X}}$ yields
 - Gaussian tail for $\lambda_{\max}(\mathbf{X})$ for small t , Poisson tail for large t
- When $d = 1$, reduces to scalar result of Chatterjee (2007)
- The dimensional factor d cannot be removed

Application: Matrix Hoeffding Inequality

Corollary (Mackey, Jordan, Chen, Farrell, and Tropp, 2012)

Let $(\mathbf{Y}_k)_{k \geq 1}$ be independent matrices in \mathbb{H}^d satisfying

$$\mathbb{E} \mathbf{Y}_k = \mathbf{0} \quad \text{and} \quad \mathbf{Y}_k^2 \preceq \mathbf{A}_k^2$$

for deterministic matrices $(\mathbf{A}_k)_{k \geq 1}$. Define the variance parameter

$$\sigma^2 := \frac{1}{2} \left\| \sum_k (\mathbf{A}_k^2 + \mathbb{E} \mathbf{Y}_k^2) \right\|.$$

Then, for all $t \geq 0$,

$$\mathbb{P} \left\{ \lambda_{\max} \left(\sum_k \mathbf{Y}_k \right) \geq t \right\} \leq d \cdot e^{-t^2/2\sigma^2}.$$

- Improves upon the matrix Hoeffding inequality of Tropp (2011)
 - Optimal constant $1/2$ in the exponent
 - Variance parameter σ^2 smaller than the bound $\left\| \sum_k \mathbf{A}_k^2 \right\|$
- Tighter than classical Hoeffding inequality (1963) when $d = 1$

Exponential Concentration: Proof Sketch

1. Matrix Laplace transform method (Ahlsvede & Winter, 2002)

- Relate tail probability to the *trace* of the mgf of \mathbf{X}

$$\mathbb{P}\{\lambda_{\max}(\mathbf{X}) \geq t\} \leq \inf_{\theta > 0} e^{-\theta t} \cdot m(\theta)$$

where $m(\theta) := \mathbb{E} \operatorname{tr} e^{\theta \mathbf{X}}$

How to bound the trace mgf?

- Past approaches: Golden-Thompson, Lieb's concavity theorem
- Chatterjee's strategy for scalar concentration
 - Control mgf growth by bounding derivative

$$m'(\theta) = \mathbb{E} \operatorname{tr} \mathbf{X} e^{\theta \mathbf{X}} \quad \text{for } \theta \in \mathbb{R}.$$

- Rewrite using exchangeable pairs

Method of Exchangeable Pairs

Lemma

Suppose that $(\mathbf{X}, \mathbf{X}')$ is a matrix Stein pair with scale factor α . Let $\mathbf{F} : \mathbb{H}^d \rightarrow \mathbb{H}^d$ be a measurable function satisfying

$$\mathbb{E}\|(\mathbf{X} - \mathbf{X}')\mathbf{F}(\mathbf{X})\| < \infty.$$

Then

$$\mathbb{E}[\mathbf{X} \mathbf{F}(\mathbf{X})] = \frac{1}{2\alpha} \mathbb{E}[(\mathbf{X} - \mathbf{X}')(\mathbf{F}(\mathbf{X}) - \mathbf{F}(\mathbf{X}'))]. \quad (1)$$

Intuition

- Can characterize the distribution of a random matrix by integrating it against a class of test functions \mathbf{F}
- Eq. 1 allows us to estimate this integral using the smoothness properties of \mathbf{F} and the discrepancy $\mathbf{X} - \mathbf{X}'$

Exponential Concentration: Proof Sketch

2. Method of Exchangeable Pairs

- Rewrite the derivative of the trace mgf

$$m'(\theta) = \mathbb{E} \operatorname{tr} \mathbf{X} e^{\theta \mathbf{X}} = \frac{1}{2\alpha} \mathbb{E} \operatorname{tr} [(\mathbf{X} - \mathbf{X}') (e^{\theta \mathbf{X}} - e^{\theta \mathbf{X}'})].$$

Goal: Use the smoothness of $F(\mathbf{X}) = e^{\theta \mathbf{X}}$ to bound the derivative

Mean Value Trace Inequality

Lemma (Mackey, Jordan, Chen, Farrell, and Tropp, 2012)

Suppose that $g : \mathbb{R} \rightarrow \mathbb{R}$ is a weakly increasing function and that $h : \mathbb{R} \rightarrow \mathbb{R}$ is a function whose derivative h' is convex. For all matrices $\mathbf{A}, \mathbf{B} \in \mathbb{H}^d$, it holds that

$$\begin{aligned} \operatorname{tr}[(g(\mathbf{A}) - g(\mathbf{B})) \cdot (h(\mathbf{A}) - h(\mathbf{B}))] &\leq \\ \frac{1}{2} \operatorname{tr}[(g(\mathbf{A}) - g(\mathbf{B})) \cdot (\mathbf{A} - \mathbf{B}) \cdot (h'(\mathbf{A}) + h'(\mathbf{B}))]. \end{aligned}$$

- *Standard matrix functions:* If $g : \mathbb{R} \rightarrow \mathbb{R}$, then

$$g(\mathbf{A}) := \mathbf{Q} \begin{bmatrix} g(\lambda_1) & & \\ & \ddots & \\ & & g(\lambda_d) \end{bmatrix} \mathbf{Q}^* \quad \text{when} \quad \mathbf{A} := \mathbf{Q} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_d \end{bmatrix} \mathbf{Q}^*$$

- Inequality does not hold without the trace
- For exponential concentration we let $g(\mathbf{A}) = \mathbf{A}$ and $h(\mathbf{B}) = e^{\theta \mathbf{B}}$

Exponential Concentration: Proof Sketch

3. Mean Value Trace Inequality

- Bound the derivative of the trace mgf

$$\begin{aligned}
 m'(\theta) &= \frac{1}{2\alpha} \mathbb{E} \operatorname{tr} [(\mathbf{X} - \mathbf{X}') (e^{\theta \mathbf{X}} - e^{\theta \mathbf{X}'})] \\
 &\leq \frac{\theta}{4\alpha} \mathbb{E} \operatorname{tr} [(\mathbf{X} - \mathbf{X}')^2 \cdot (e^{\theta \mathbf{X}} + e^{\theta \mathbf{X}'})] \\
 &= \theta \cdot \mathbb{E} \operatorname{tr} [\Delta_{\mathbf{X}} e^{\theta \mathbf{X}}].
 \end{aligned}$$

4. Conditional Variance Bound: $\Delta_{\mathbf{X}} \preceq c\mathbf{X} + v\mathbf{I}$

- Yields differential inequality

$$m'(\theta) \leq c\theta \cdot m'(\theta) + v\theta \cdot m(\theta).$$

- Solve to bound $m(\theta)$ and thereby bound $\mathbb{P}\{\lambda_{\max}(\mathbf{X}) \geq t\}$

Polynomial Moments for Random Matrices

Theorem (Mackey, Jordan, Chen, Farrell, and Tropp, 2012)

Let $p = 1$ or $p \geq 1.5$. Suppose that $(\mathbf{X}, \mathbf{X}')$ is a matrix Stein pair where $\mathbb{E}\|\mathbf{X}\|_{2p}^{2p} < \infty$. Then

$$\left(\mathbb{E}\|\mathbf{X}\|_{2p}^{2p}\right)^{1/2p} \leq \sqrt{2p-1} \cdot \left(\mathbb{E}\|\Delta_{\mathbf{X}}\|_p^p\right)^{1/2p}.$$

- **Moral:** The conditional variance controls the moments of \mathbf{X}
- Generalizes Chatterjee's version (2007) of the scalar Burkholder-Davis-Gundy inequality (Burkholder, 1973)
 - See also Pisier & Xu (1997); Junge & Xu (2003, 2008)
- Proof techniques mirror those for exponential concentration
- Also holds for infinite dimensional Schatten-class operators

Application: Matrix Khintchine Inequality

Corollary (Mackey, Jordan, Chen, Farrell, and Tropp, 2012)

Let $(\varepsilon_k)_{k \geq 1}$ be an independent sequence of Rademacher random variables and $(\mathbf{A}_k)_{k \geq 1}$ be a deterministic sequence of Hermitian matrices. Then if $p = 1$ or $p \geq 1.5$,

$$\left(\mathbb{E} \left\| \sum_k \varepsilon_k \mathbf{A}_k \right\|_{2p}^{2p} \right)^{1/2p} \leq \sqrt{2p-1} \cdot \left\| \left(\sum_k \mathbf{A}_k^2 \right)^{1/2} \right\|_{2p}.$$

- Noncommutative Khintchine inequality (Lust-Piquard, 1986; Lust-Piquard and Pisier, 1991) is a dominant tool in applied matrix analysis
 - e.g., Used in analysis of column sampling and projection for approximate SVD (Rudelson and Vershynin, 2007)
- Stein's method offers an unusually concise proof
- The constant $\sqrt{2p-1}$ is within \sqrt{e} of optimal

Extensions

Refined Exponential Concentration

- Relate trace mgf of conditional variance to trace mgf of \mathbf{X}
- Yields matrix generalization of classical Bernstein inequality
- Offers tool for unbounded random matrices

General Complex Matrices

- Map any matrix $\mathbf{B} \in \mathbb{C}^{d_1 \times d_2}$ to a Hermitian matrix via *dilation*

$$\mathcal{D}(\mathbf{B}) := \begin{bmatrix} \mathbf{0} & \mathbf{B} \\ \mathbf{B}^* & \mathbf{0} \end{bmatrix} \in \mathbb{H}^{d_1+d_2}.$$

- Preserves spectral information: $\lambda_{\max}(\mathcal{D}(\mathbf{B})) = \|\mathbf{B}\|$

Dependent Sequences

- Sums of conditionally zero-mean random matrices
- Combinatorial matrix statistics (e.g., sampling w/o replacement)
- Matrix-valued functions satisfying a self-reproducing property
 - Yields a dependent bounded differences inequality for matrices

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