

AN ALGORITHM TO COMPUTE THE CENTERED HAUSDORFF MEASURE OF SELF-SIMILAR SETS

Fractals and Related Fields II

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¹Joint work with M. Morán

Self-similar sets

- $\Psi = \{f_1, f_2, \dots, f_m\}$ a system of contracting similitudes of \mathbb{R}^n
Self-similar set E : The unique ($\neq \emptyset$) compact set satisfying

$$E = \bigcup_{i=1}^m f_i(E)$$

- **Open set condition (OSC)** :

$$\exists \mathcal{O} \subset \mathbb{R}^n \text{ open} : \begin{cases} f_i(\mathcal{O}) \subset \mathcal{O} \quad i = 1, \dots, m \\ f_i(\mathcal{O}) \cap f_j(\mathcal{O}) = \emptyset \text{ for } i \neq j. \end{cases}$$

- Ψ satisfies the **strong separation condition (SSC)**, if $f_i(E) \cap f_j(E) = \emptyset \quad \forall i \neq j$.

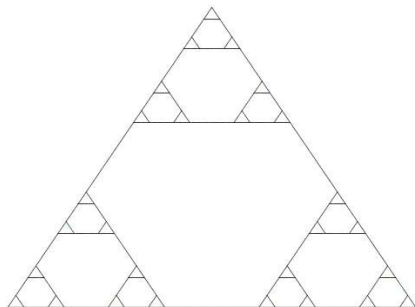
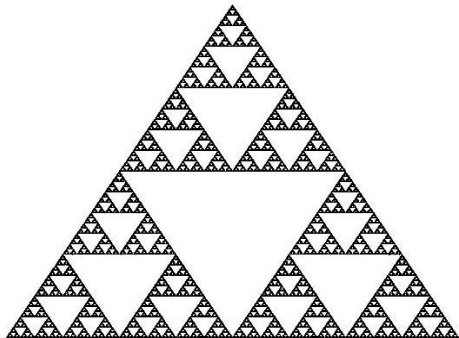
Geometric interpretation: OSC-SSC

OSC \equiv If the pieces of the self-similar set (*basic cylinder sets*), do intersect, this intersection is "small" :

$$H^s(f_i(E) \cap f_j(E)) = 0 \quad \forall i \neq j,$$

where $s = \dim E$ y $H^s(E)$ is the s -dimensional Hausdorff measure.

SSC \equiv The pieces of the self-similar set (*basic cylinder sets*) are disjoint

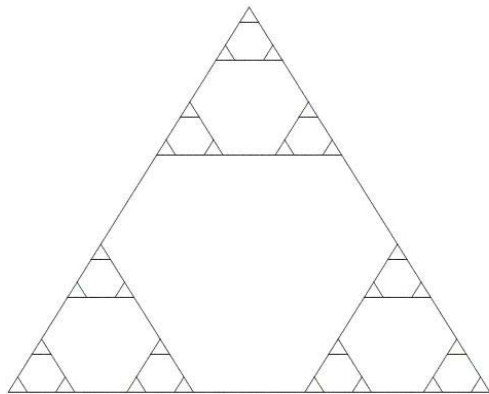
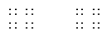
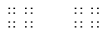


$$\text{OSC} \implies \begin{cases} \dim_H E = s \begin{cases} s \text{ is the solution } \sum_{i=1}^m r_i^s = 1, \\ r_i \text{ is the contraction ratio of } f_i \end{cases} \\ 0 < H^s(E) < \infty. \end{cases} .$$

SSC \implies invariant set E is totally disconnected (Euclidean metric)

Two self-similar sets of the same dimension ($\sum_{i=1}^m r_i^s = 1$)

$$\dim_H C(1/4) = 1 = \dim_H S(1/3)$$



Two equivalent measures: $2^{-s}C^s(E) \leq H^s(E) \leq C^s(E)$

Hausdorff measure

$$H^s(E) = \lim_{\varepsilon \rightarrow 0} \left[\inf \left\{ \sum_{i=1}^{\infty} |U_i|^s : |U_i| \leq \varepsilon, E \subset \cup U_i \right\} \right]$$

Hausdorff centered measure

$$C_0^s(E) = \lim_{\varepsilon \rightarrow 0} \left[\inf \left\{ \sum_{i=1}^{\infty} |B_i|^s : |B_i| \leq \varepsilon, E \subset \cup B_i, \right. \right. \\ \left. \left. B_i \text{ closed balls centered in } E \right\} \right]$$

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$C_0^s(E)$ not monotone !!!!

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$C_0^s(E)$ not monotone !!!!

$$C^s(E) = \sup \{ C_0^s(F) : F \subset E \} \text{ (Measure)}$$

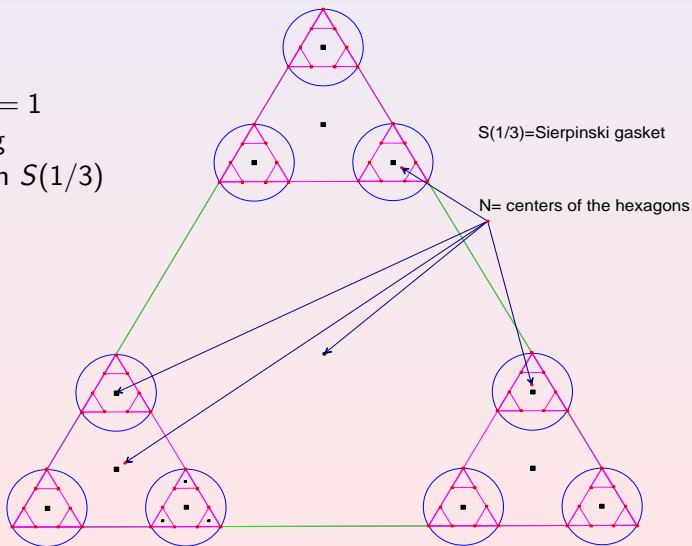
EXAMPLE: $C_0^s(S(1/3) \cup N) < C_0^s(S(1/3))$ [Tricot ('82)]

$$s = \dim_H(S(1/3)) = 1$$

Any other covering
by balls centered in $S(1/3)$
is less efficient!!

$$N = \bigcup_{i=1}^{\infty} x_i$$

$$H^1(N) = 0$$



Two Steps Measures:

If E is the self-similar set associated to the system $\Psi = \{f_1, f_2, \dots, f_m\}$ satisfying the OSC with $\dim_H E = s$.

Theorem (LL. and Morán (´10))

If $F \subset E$ either closed or open. Then $C_0^s F = C^s F$.

Two Steps Measures:

Packing measure $P^s(E) = \inf \left\{ \sum_{i=1}^{\infty} P_0^s(F_i) : E \subset \bigcup_{i=1}^{\infty} F_i \right\}$

$$P_0^s(E) = \lim_{\varepsilon \rightarrow 0} \left[\sup \left\{ \sum_{i=1}^n |B_i|^s : |B_i| \leq \varepsilon, B_i \cap B_j = \emptyset \right. \right. \\ \left. \left. \text{for } i \neq j, B_i \text{ closed balls centered in } E \right\} \right]$$

[Feng ('98)]: If K is compact: $P_0^s(K) < \infty \implies P_0^s(K) = P^s(K)$

$C^s(E), P^s(E)$ two step definition $\begin{cases} C_0^s(E) \text{ not monotone} \\ P_0^s(E) \text{ not } \sigma\text{-subadditive} \end{cases}$

The Lemma is false for general compact sets

Two Steps Measures:

Example

$\exists S \subset \mathbb{R}^n$ compact set : $C^s S > C_0^s S$.

$$C^1(S(1/3) \cup N) = C^1(S(1/3)) = C_0^1(S(1/3)) > C_0^1(S(1/3) \cup N)$$

since, the previous theorem

$$C^1(S(1/3)) = C_0^1(S(1/3))$$

and

$$C^1(N) = 0$$

$$(\dim_H(S(1/3)) = 1)$$

Program to compute $C^s(E)$

STEP 1: ¿Optimal coverings? → **Optimization of density functions**

STEP 2: **Discretization of the problem** to construct an algorithm that converges to $C^s(E)$

Program to compute $C^s(E)$

STEP 1: ¿Optimal coverings? → **Optimization of density functions**

TOOLS: $\left\{ \begin{array}{l} 1. C_0^s F = C^s F \text{ (LL. \& Morán ('10))} \\ 2. \text{Self-similar tiling principle (Morán ('04))} \\ 3. \text{Invariance of the density functions} \end{array} \right.$

$$\implies C^s E = \min \left\{ \frac{(2r)^s}{\mu(B(x, r))} : x \in E \text{ and } c \leq r \leq R \right\}$$

STEP 2: **Discretization of the problem** to construct an algorithm that converges to $C^s(E)$

Program to compute $C^s(E)$: **STEP 1**

[Ayer and Stricharz ('99)]: *Exact Hausdorff measure and intervals of maximum density for Cantor sets*

[Morán ('04)]: *Computability of the Hausdorff and packing measures on self-similar sets and the self-similar tiling principle*

Program to compute $C^s(E)$: **STEP 1**

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$$H^s(E) \rightarrow \frac{H^s(E \cap I)}{|I|^s} = d(I)$$

$I \subset [0, 1] \rightarrow$ interval that maximizes the density

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$$\text{OSC} \begin{cases} H^s(E) = \inf\{|A|^s/\mu A : A \text{ is a convex polytope}\} \\ H_{sph}^s(E) = \inf\{2r^s/\mu B(x, r) : x \in \mathbb{R}^n\} \\ P^s(E) = \sup\{(2r)^s/\mu B(x, r) : x \in E, B(x, r) \subset \mathcal{O}\}. \end{cases}$$

$\mu = \frac{H_{\perp E}^s}{H^s(E)} \rightarrow$ natural probability measure on E [$\mu(f_i(E)) = r_i^s$].

Program to compute $C^s(E)$: **STEP 1**

Theorem (LL. and Morán ('10))

Let E be the invariant set of the system Ψ satisfying the open set with $\dim_{\mathbb{H}} E = s$ and $|E| = R$ and let μ be the Hausdorff normalized measure on E . Then

$$C^s E = \inf \left\{ \frac{(2r)^s}{\mu(B(x, r))} : x \in E, r > 0 \right\} =: D_C^{-1} \quad (1)$$

Moreover, if Ψ satisfies the **SSC** then

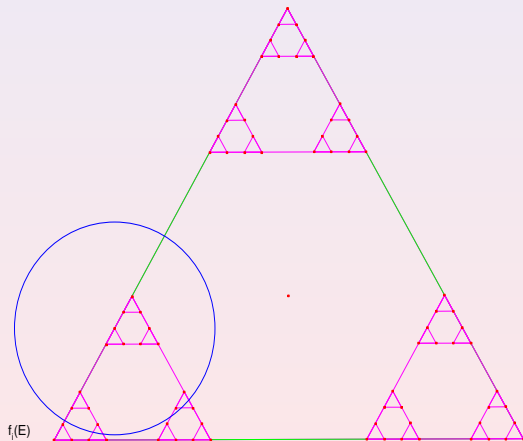
$$C^s E = \min \left\{ \frac{(2r)^s}{\mu(B(x, r))} : x \in E \text{ and } c \leq r \leq R \right\}$$

where $c := \min_{i, j \in M, i \neq j} \text{dist}(f_i E, f_j E)$ and $R := |E|$.

Program to compute $C^s(E)$: **STEP 1**

$$\mu(f_i(E)) = r_i^s \mu(E)$$

$$\frac{(2r/r_i)^s}{\mu(f_i(B))} = \frac{(2r)^s}{\mu(B)}$$



Program to compute $C^s(E)$: **STEP 2**

Knowing that

$$C^s(E) = \min\{f_s(x, d) = \frac{(2d)^s}{\mu(B(x, d))} : x \in E, d \in [c, 1]\}$$

We construct:

- 1 a sequence $\{A_k\}$ of sets and a sequence $\{\mu_k\}$ of measures s.t.

$$\text{spt}(\mu_k) = A_k \quad \mu_k \rightarrow \mu \quad \text{and} \quad E = \overline{\bigcup_{k=1}^{\infty} A_k}$$

- 2 with these sequences we construct another sequence $\{\widetilde{m}_k\}$

$$\widetilde{m}_k = f_k(\widetilde{x}_k, \widetilde{d}_k) = \min\{f_k(x_k, d_k) : d_k = \|x_k - y_k\|, (x_k, y_k) \in A_k \times A_k\}$$

$$\text{where } f_k(x_k, d_k) = \frac{(2d_k)^s}{\mu_k(B(x_k, d_k))}$$

Theorem (LL. and Morán ('10/'11))

$$\widetilde{m}_k \rightarrow C^s(E) \text{ as } k \rightarrow \infty$$

$$A_1 = \{x_0, x_1, x_2\}$$

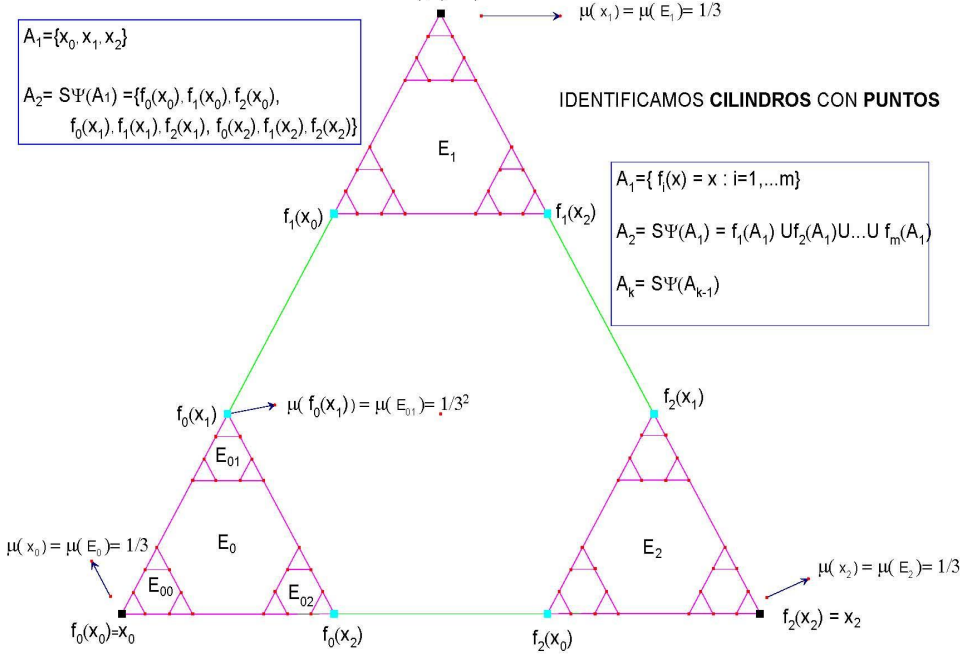
$$A_2 = S\Psi(A_1) = \{f_0(x_0), f_1(x_0), f_2(x_0), f_0(x_1), f_1(x_1), f_2(x_1), f_0(x_2), f_1(x_2), f_2(x_2)\}$$

IDENTIFICAMOS **CILINDROS CON PUNTOS**

$$A_1 = \{f_i(x) = x : i=1, \dots, m\}$$

$$A_2 = S\Psi(A_1) = f_1(A_1) \cup f_2(A_1) \cup \dots \cup f_m(A_1)$$

$$A_k = S\Psi(A_{k-1})$$



Examples: testing efficiency

λ -Cantor sets on the real line $K(\lambda) = \cup_{i=0}^1 f_i(K(\lambda))$:

$$f_0(x) = \lambda x, \quad f_1(x) = 1 - \lambda + \lambda x, \quad x \in [0, 1]$$

[Zhu & Zhou ('02)]:

$$C^s(K(\lambda)) = 2^s(1 - \lambda)^s \quad \forall 0 < \lambda \leq \frac{1}{3} \quad s = \frac{\log 2}{-\log \lambda}$$

$$K\left(\frac{1}{3}\right) - \text{Middle-third Cantor set: } C^s(K\left(\frac{1}{3}\right)) = \frac{4^{\frac{\log 2}{\log 3}}}{2} \simeq 1.199023$$

The algorithm finds the exact value of $C^s(K(\frac{1}{3}))$ already at the third iteration!!!: $\forall k \geq 2$ the two minimizing intervals selected, $[-\frac{1}{3}, 1]$ and $[0, \frac{4}{3}]$, verify

$$f_k\left(\frac{1}{3}, \frac{2}{3}\right) = f_k\left(\frac{2}{3}, \frac{2}{3}\right) = \frac{(2\frac{2}{3})^s}{1} = \frac{4^{\frac{\log 2}{\log 3}}}{2} = C^s(K\left(\frac{1}{3}\right)).$$

Examples: Middle-third Cantor set

k	\tilde{m}_k	$(\tilde{x}_k, \tilde{y}_k)$	\tilde{d}_k	$B(\tilde{x}_k, \tilde{d}_k)$
0	1.54856	$(0, 1)$ $(1, 0)$	1	$[-1, 1]$
1	1.03238	$(\frac{2}{3}, \frac{1}{3})$ $(\frac{1}{3}, \frac{2}{3})$	0.333333	$[\frac{1}{3}, 1]$ $[0, \frac{2}{3}]$
2	1.19902	$(\frac{2}{3}, 0)$ $(\frac{1}{3}, 1)$	0.666667	$[0, \frac{4}{3}]$ $[-\frac{1}{3}, 1]$
3	1.19902	$(\frac{2}{3}, 0)$ $(\frac{1}{3}, 1)$	0.666667	$[0, \frac{4}{3}]$ $[-\frac{1}{3}, 1]$
4	1.19902	$(\frac{2}{3}, 0)$ $(\frac{1}{3}, 1)$	0.666667	$[0, \frac{4}{3}]$ $[-\frac{1}{3}, 1]$
5	1.19902	$(\frac{2}{3}, 0)$ $(\frac{1}{3}, 1)$	0.666667	$[0, \frac{4}{3}]$ $[-\frac{1}{3}, 1]$

Examples: Conclusions

Testing the algorithm for the known cases

- λ -Cantor sets on the real line [Zhu & Zhou ('02)]
- (λ_1, λ_2) -Symmetry Cantor sets on the real line [Dai & Tian ('05)]
- Cantor type sets on the plane [Zhu & Zhou ('08)]

All of them have extra conditions \implies the contraction factors are quite small \implies the algorithm finds the exact value very quickly as

$$\mu(B(\tilde{x}_k, \tilde{d}_k)) = \mu_k(B(\tilde{x}_k, \tilde{d}_k)) = 1!!!!$$

(the optimal ball does not cut any cylinder set as it contains the whole set, so one can find a way to compute them "by hand")

This seems to be a general rule!!!!

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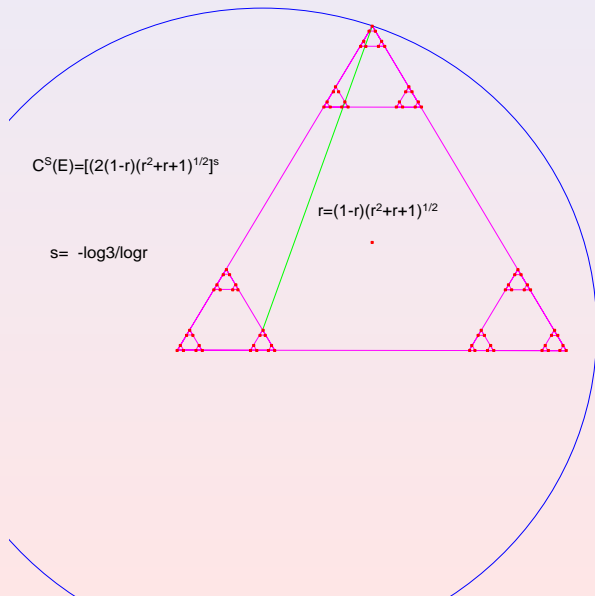
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Examples: Sierpinski with $r < 0.25$



Examples: Self-similar sets with dimension ≥ 1

The optimal ball changes slightly: the center is fixed and the radius changes slightly

- $S(\frac{1}{3})$ -Sierpinski gasket, ($r = \frac{1}{3}$, $\dim_H = 1$)

$$C^1(S(\frac{1}{3})) \simeq 1.54$$

- $C(\frac{1}{4})$ -Cantor set in the plane, ($r = \frac{1}{4}$, $\dim_H = 1$)

$$C^1(S(\frac{1}{3})) \simeq 1.95$$

{2.66667, 1.92296, 1.95814, 1.95542, 1.95306, 1.95388, 1.95417}

- $C(\frac{4}{10})$ -Cantor set in the plane, $r = \frac{4}{10}$, $\dim_H = \frac{-\log 4}{\log 0.4} \simeq 1.51294$

$$C^{\frac{-\log 4}{\log 0.4}}(S(\frac{1}{3})) \simeq 1.64$$

{3.80522, 1.33333, 1.59995, 1.6425, 1.64928, 1.64807, 1.64972}

$$C^1(C(\frac{1}{4})) \simeq 1.95$$

